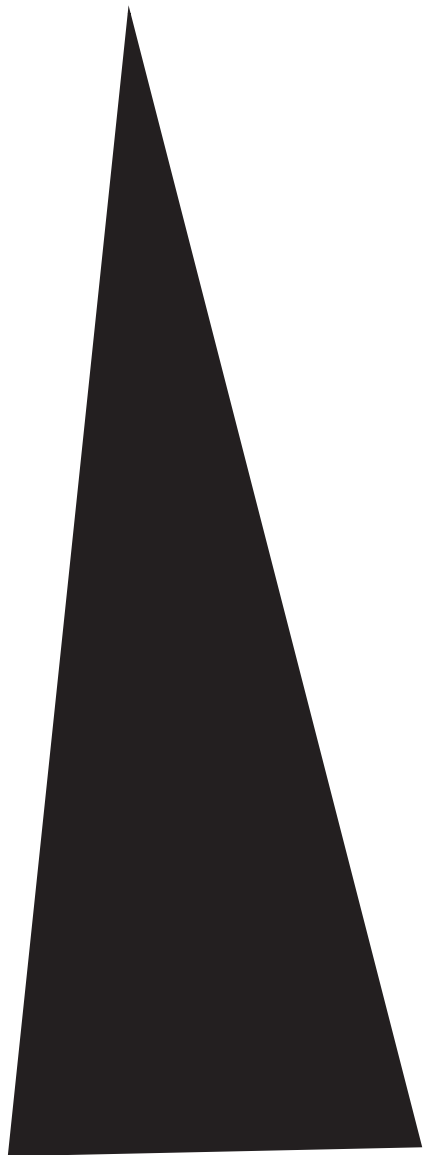


○ Size of robot

Start +



Goal +

